MATH 217 SPRING 2014 WRITTEN HOMEWORK 4 SOLUTIONS

SECTION 2.1

Problem 13.

(a) If $a \neq 0$, then $\begin{bmatrix} a & b \\ c & d \end{bmatrix}$ is row-equivalent to $\begin{bmatrix} 1 & b/a \\ 0 & d - (bc)/a \end{bmatrix}$. If ad - bc = 0, then there is a row of 0s in rref and the matrix is not invertible. If ad - bc = 0, then the matrix is invertible.

If a=0 and c=0, then the matrix has a column of 0s and it cannot be invertible. If a=0 and $c\neq 0$, then $\begin{bmatrix} 0 & b \\ c & d \end{bmatrix}$ is row-equivalent to $\begin{bmatrix} 1 & d/c \\ 0 & b \end{bmatrix}$. In this case $ad-bc\neq 0$ if and only if $bc\neq 0$ if and only if $b\neq 0$. Observe that there is a second pivot and the matrix is invertible if and only if $b\neq 0$.

(b) Suppose $\begin{bmatrix} a & b \\ c & d \end{bmatrix}$ is invertible. From (a), we know $ad-bc \neq 0$. Let $B = \frac{1}{ad-bc} \begin{bmatrix} d & -b \\ -c & a \end{bmatrix}$. It is easy to check that AB = I and BA = I. So B is the inverse of A.

Alternate Solution : We can show that if $a \neq 0$, $\begin{bmatrix} a & b & 1 & 0 \\ c & d & 0 & 1 \end{bmatrix}$ is row-equivalent to $\begin{bmatrix} 1 & b/a & 1/a & 0 \\ 0 & d - (bc)/a & -c/a & 1 \end{bmatrix}$. There is no second pivot if ad - bc = 0 and the matrix is not

invertible. If $ad-bc \neq 0$, then the augmented matrix is row-equivalent to $\begin{bmatrix} 1 & 0 & d/(ad-bc) & -b/(ad-bc) \\ 0 & 1 & -c/(ad-bc) & a/(ad-bc) \end{bmatrix}$. The inverse must be $\frac{1}{ad-bc} \begin{bmatrix} d & -b \\ -c & a \end{bmatrix}$.

If a=0 and c=0, there is no second pivot and the matrix is not invertible. If a=0 and $c\neq 0$, $\begin{bmatrix} 0 & b & 1 & 0 \\ c & d & 0 & 1 \end{bmatrix}$ is row-equivalent to $\begin{bmatrix} 1 & d/c & 0 & 1/c \\ 0 & 1 & 1/b & 0 \end{bmatrix}$.

If b=0, there is no second pivot and the matrix is not invertible. If $b\neq 0$, the augmented matrix is row-equivalent to $\begin{bmatrix} 1 & 0 & -d/bc & 1/c \\ 0 & 1 & 1/b & 0 \end{bmatrix}$. Then the inverse is $\frac{1}{-bc}\begin{bmatrix} d & -b \\ -c & 0 \end{bmatrix}$ which is of the form $\frac{1}{ad-bc}\begin{bmatrix} d & -b \\ -c & a \end{bmatrix}$ when a=0 and $ad-bc=-bc\neq 0$.

Problem 58.

(a) Let the masses of platinum and silver be x and y grams respectively. Then

$$\begin{array}{ccccc} x & + & y & = & 5000 \\ \frac{x}{20} & + & \frac{y}{10} & = & 370 \end{array}$$

The augmented matrix $\begin{bmatrix} 1 & 1 & 5000 \\ 1/20 & 1/10 & 370 \end{bmatrix}$ has rref $\begin{bmatrix} 1 & 0 & 2600 \\ 0 & 1 & 2400 \end{bmatrix}$

The mass of platinum is 2600 grams and the mass of silver is 2400 grams, which means there is only 52% platinum and the goldsmith is a crook.

- (b) From part (a), $A = \begin{bmatrix} 1 & 1 \\ 1/20 & 1/10 \end{bmatrix}$.
- (c) A is a 2×2 matrix with rank 2, so A is invertible. Alternatively using 2.1.13, A is invertible because $ad bc = 1/20 \neq 0$.

$$A^{-1} = \begin{bmatrix} 2 & -20 \\ -1 & 20 \end{bmatrix}$$

The unique solution to $A \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 5000 \\ 370 \end{bmatrix}$ must be $\begin{bmatrix} x \\ y \end{bmatrix} = A^{-1} \begin{bmatrix} 5000 \\ 370 \end{bmatrix} = \begin{bmatrix} 2600 \\ 2400 \end{bmatrix}$.

SECTION 2.2

Problem 8. $\begin{bmatrix} 0 & -1 \\ -1 & 0 \end{bmatrix}$ is of the form $\begin{bmatrix} a & b \\ b & -a \end{bmatrix}$ with a = 0 and b = -1. Since $a^2 + b^2 = 1$,

this matrix represents a reflection about a line. Comparing with the form $\begin{bmatrix} 2u_1^2 - 1 & 2u_1u_2 \\ 2u_1u_2 & 2u_2^2 - 1 \end{bmatrix}$,

we see that $\mathbf{u} = \begin{bmatrix} \frac{1}{\sqrt{2}} \\ -\frac{1}{\sqrt{2}} \end{bmatrix}$ or $\mathbf{u} = \begin{bmatrix} -\frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} \end{bmatrix}$. The line is y = -x.

Problem 12.

- (a) Since A is a reflection matrix, $A(A\mathbf{x}) = \mathbf{x}$.
- (b) $A\mathbf{v} = A(\mathbf{x} + A\mathbf{x}) = A\mathbf{x} + A(A\mathbf{x}) = A\mathbf{x} + \mathbf{x} = \mathbf{v}$.
- (c) $A\mathbf{w} = A(\mathbf{x} A\mathbf{x}) = A\mathbf{x} A(A\mathbf{x}) = A\mathbf{x} \mathbf{x} = -\mathbf{w}$.
- (d) If \mathbf{v} is a non-zero vector and its reflection is itself, then \mathbf{v} must be parallel to the line of reflection. If \mathbf{w} is a non-zero vector and its reflection is the opposite vector $-\mathbf{w}$, then \mathbf{w} must be perpendicular to the line of reflection. So the angle between \mathbf{v} and \mathbf{w} is $\pi/2$.
- (e) See part (d).

Problem 20. Let T be the reflection about the xz-plane. Since \mathbf{e}_1 and \mathbf{e}_3 are parallel to the xz-plane and \mathbf{e}_2 is perpendicular to the xz-plane, $T(\mathbf{e}_1) = \mathbf{e}_1$, $T(\mathbf{e}_2) = -\mathbf{e}_2$ and $T(\mathbf{e}_3) = \mathbf{e}_3$. Using Theorem 2.1.2, the matrix of T is

$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 1 \end{bmatrix}.$$

Alternate Solution : Let T be the reflection about the xz-plane.

$$T \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} x \\ -y \\ z \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix}$$

By definition, the matrix of T must be $\begin{bmatrix} 1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$.

Problem 26.

- (a) The scaling factor is 4, so $A = 4I_2 = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$.
- (b) The projected vector $\begin{bmatrix} 2 \\ 0 \end{bmatrix}$ is parallel to the *x*-axis, so *B* is the matrix of orthogonal projection onto the *x*-axis. $B = \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}$.
- (c) Rotation matrix C is of the form $\begin{bmatrix} a & -b \\ b & a \end{bmatrix}$ and $C \begin{bmatrix} 0 \\ 5 \end{bmatrix} = \begin{bmatrix} -5b \\ 5a \end{bmatrix} = \begin{bmatrix} 3 \\ 4 \end{bmatrix}$. This implies b = -0.6, a = 0.8 and $C = \begin{bmatrix} 0.8 & 0.6 \\ -0.6 & 0.8 \end{bmatrix}$
- (d) Since the second co-ordinate remains the same after transformation, D represents a horizontal shear. D is of the form $\begin{bmatrix} 1 & k \\ 0 & 1 \end{bmatrix}$ and $D \begin{bmatrix} 1 \\ 3 \end{bmatrix} = \begin{bmatrix} 1+3k \\ 3 \end{bmatrix} = \begin{bmatrix} 7 \\ 3 \end{bmatrix}$. This implies k=2 and $D=\begin{bmatrix} 1 & 2 \\ 0 & 1 \end{bmatrix}$.
- (e) Reflection matrix E is of the form $\begin{bmatrix} a & b \\ b & -a \end{bmatrix}$ and $E \begin{bmatrix} 7 \\ 1 \end{bmatrix} = \begin{bmatrix} 7a+b \\ 7b-a \end{bmatrix}$.

 The linear system $\begin{bmatrix} 7 & 1 \\ -1 & 7 \end{bmatrix} \begin{bmatrix} a \\ b \end{bmatrix} = \begin{bmatrix} -5 \\ 5 \end{bmatrix}$ has the solution a = -0.8 and b = 0.6 and $E = \begin{bmatrix} -0.8 & 0.6 \\ 0.6 & 0.8 \end{bmatrix}$.

SECTION 2.3

Problem 14. The products AB, AC, AD, AE, BA, B^2 , BE, CA, CB, CE, DA, DC, D^2 , EA, EC, ED are not defined because the number of columns in the first matrix does not equal number of rows in the second matrix.

$$A^{2} = \begin{bmatrix} 2 & 2 \\ 2 & 2 \end{bmatrix} \qquad BC = \begin{bmatrix} 14 & 8 & 2 \end{bmatrix} \qquad BD = \begin{bmatrix} 6 \end{bmatrix}$$

$$C^{2} = \begin{bmatrix} -2 & -2 & -2 \\ 4 & 1 & -2 \\ 10 & 4 & -2 \end{bmatrix} \qquad CD = \begin{bmatrix} 0 \\ 3 \\ 6 \end{bmatrix} \qquad DB = \begin{bmatrix} 1 & 2 & 3 \\ 1 & 2 & 3 \\ 1 & 2 & 3 \end{bmatrix} \qquad DE = \begin{bmatrix} 5 \\ 5 \\ 5 \end{bmatrix}$$

$$EB = \begin{bmatrix} 5 & 10 & 15 \end{bmatrix} \qquad E^{2} = \begin{bmatrix} 25 \end{bmatrix}$$

Problem 38.

$$A^{2} = \begin{bmatrix} -1/2 & \sqrt{3}/2 \\ -\sqrt{3}/2 & -1/2 \end{bmatrix} \qquad A^{3} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \qquad A^{4} = \begin{bmatrix} -1/2 & -\sqrt{3}/2 \\ \sqrt{3}/2 & -1/2 \end{bmatrix}$$

The pattern is $A^{3k} = I_2$, $A^{3k+1} = A$, $A^{3k+2} = A^2$ for all $k \in \mathbb{N}$. A has the form of a rotation matrix $\begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix}$ with $\cos \theta = -1/2$ and $\sin \theta = \sqrt{3}/2$, therefore the angle of rotation $\theta = 2\pi/3$. Rotation by $4\pi/3$ has matrix $A^2 = \sqrt{3}/2$. $\begin{bmatrix} -1/2 & \sqrt{3}/2 \\ -\sqrt{3}/2 & -1/2 \end{bmatrix}$. Rotation by $6\pi/3 = 2\pi$ is the identity transformation and it has matrix $A^3 = I_2$. Then the pattern repeats.

Problem 46. Let $T: \mathbb{R}^2 \to \mathbb{R}^2$ be an orthogonal projection onto a line L through the origin. Then $T(T(\mathbf{x})) = T(\mathbf{x})$ for all $\mathbf{x} \in \mathbb{R}^2$. A^2 is the matrix of $T \circ T = T^2$, but $T^2 = T$ implies $A^2 = A$. We can choose the projection matrix for any line such that all entries are non-zero, for example, $\begin{bmatrix} 1/2 & 1/2 \\ 1/2 & 1/2 \end{bmatrix}$ which represents projection onto y = x.

SECTION 2.4

Problem 20. Let $T: \mathbb{R}^3 \to \mathbb{R}^3$ be the linear transformation such that $\mathbf{y} = T(\mathbf{x})$. Then the matrix of T is

$$A = \begin{bmatrix} 1 & 3 & 3 \\ 1 & 4 & 8 \\ 2 & 7 & 12 \end{bmatrix}$$

Performing Gauss-Jordan elimination on $\begin{bmatrix} 1 & 3 & 3 & | & 1 & 0 & 0 \\ 1 & 4 & 8 & | & 0 & 1 & 0 \\ 2 & 7 & 12 & | & 0 & 0 & 1 \end{bmatrix}$ we see that the augmented matrix has reduced row-echelon form $\begin{bmatrix} 1 & 0 & 0 & | & -8 & -15 & 12 \\ 0 & 1 & 0 & | & 4 & 6 & -5 \\ 0 & 0 & 1 & | & -1 & -1 & 1 \end{bmatrix} .$

Therefore

 $A^{-1} = \begin{bmatrix} -8 & -15 & 12 \\ 4 & 6 & -5 \\ -1 & -1 & 1 \end{bmatrix}$ is the matrix of the inverse linear transformation $T^{-1}: \mathbb{R}^3 \to \mathbb{R}^3$

and the inverse transformation is

$$x_1 = -8y_1 - 15y_2 + 12y_3$$

 $x_2 = 4y_1 + 6y_2 - 5y_3$
 $x_3 = -y_1 - y_2 + y_3$

Problem 30.
$$\begin{bmatrix} 0 & 1 & b \\ -1 & 0 & c \\ -b & -c & 0 \end{bmatrix} \longrightarrow \begin{bmatrix} 1 & 0 & -c \\ 0 & 1 & b \\ -b & -c & 0 \end{bmatrix} \longrightarrow \begin{bmatrix} 1 & 0 & -c \\ 0 & 1 & b \\ 0 & -c & -bc \end{bmatrix} \longrightarrow \begin{bmatrix} 1 & 0 & -c \\ 0 & 1 & b \\ 0 & 0 & 0 \end{bmatrix}$$

These matrices are row-equivalent for all values of b and c. The rank of the matrix is always 2 and rref $\neq I_3$. So it is never invertible.

Problem 78. We know that
$$A \begin{bmatrix} 1 \\ 2 \end{bmatrix} = \begin{bmatrix} 7 \\ 5 \\ 3 \end{bmatrix}$$
 and $A \begin{bmatrix} 2 \\ 5 \end{bmatrix} = \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}$.

Using theorem 2.3.2, we can see that AB = C where $B = \begin{bmatrix} 1 & 2 \\ 2 & 5 \end{bmatrix}$ and $C = \begin{bmatrix} 7 & 1 \\ 5 & 2 \\ 3 & 3 \end{bmatrix}$.

As $det(B) = 1(5) - 2(2) = 1 \neq 0$, B is invertible and $B^{-1} = \begin{bmatrix} 5 & -2 \\ -2 & 1 \end{bmatrix}$.

$$AB = C \quad \Leftrightarrow \quad A = CB^{-1} = \begin{bmatrix} 7 & 1 \\ 5 & 2 \\ 3 & 3 \end{bmatrix} \begin{bmatrix} 5 & -2 \\ -2 & 1 \end{bmatrix} = \begin{bmatrix} 33 & -13 \\ 21 & -8 \\ 9 & -3 \end{bmatrix}$$