

Homework 10

Due: Monday, April 11, 2011

Section 17.3, pg. 1117: 3, 9, 11, 29, 33.

Section 17.4, pg. 1125: 3, 9, 13, 25

Section 17.5, pg. 1132: 3, 12, 13

Section 17.6, pg. 1142: 3, 17, 21, 35, 45.

Solutions

17.3 # 3

Clear the derivatives are continuous, so check Clairaut's theorem. $\frac{\partial P}{\partial y} = 5$ and $\frac{\partial Q}{\partial x} = 5 = \frac{\partial P}{\partial y}$. So it is conservative. The potential function is $f(x, y) = 3x^2 + 5xy + 2y^2 + k$, where k is some constant.

17.3 # 9

$\frac{\partial P}{\partial y} = e^x + \cos y$ and $\frac{\partial Q}{\partial x} = e^x + \cos y = \frac{\partial P}{\partial y}$. So it is conservative. The potential function is $f(x, y) = ye^x + x \sin y + k$, where k is some constant.

17.3 # 11

a) $\vec{F}(x, y)$ is conservative: $\frac{\partial P}{\partial y} = \frac{\partial Q}{\partial x} = 2x$. Thus, it is path independent.

b) We don't have to use any of the given paths. Take the line $\vec{r}(t) = \langle 1 + 2t, 2 \rangle$ with $0 \leq t \leq 1$.

$$\begin{aligned} \int_C \vec{F} \cdot d\vec{r} &= \int_C P dx + \int_C Q dy \\ &= \int_0^1 2x(t)y(t)x'(t) dt + 0 \\ &= \int_0^1 2(1+2t)2 \cdot 2 dt \\ &= 8 \int_0^1 (1+2t) dt \\ &= 8(1+1) \\ &= 16 \end{aligned}$$

17.3 # 29

It's all in one piece, so it is connected. There are no holes, so it is simply-connected. The bounds (either 0 or infinity) are not part of the domain itself, so it is open.

17.3 # 33

a) $\frac{\partial P}{\partial y} = \frac{\partial Q}{\partial x} = \frac{y^2 - x^2}{(x^2 + y^2)^2}$

b) Both curves are given by $\vec{r}(t) = \langle \cos t, \sin t \rangle$. The top half has $0 \leq t \leq \pi$, and the bottom by $\pi \leq t \leq 2\pi$. Note: for C_2 , we have to progress from (1,0) to (-1,0), so the limits I've given are actually for $-C_2$.

Top path:

$$\begin{aligned} \int_{C_1} \vec{F} \cdot d\vec{r} &= \int_0^\pi P dx + \int_0^\pi Q dy \\ &= \int_0^\pi \frac{-\sin t}{\cos^2 t + \sin^2 t} (-\sin t) dt + \int_0^\pi \frac{\cos t}{\cos^2 t + \sin^2 t} (\cos t) dt \\ &= \int_0^\pi 1 dt \\ &= \pi \end{aligned}$$

Bottom path:

$$\begin{aligned} \int_{-C_2} \vec{F} \cdot d\vec{r} &= \int_{\pi}^{2\pi} P dx + \int_{\pi}^{2\pi} Q dy \\ &= \int_{\pi}^{2\pi} \frac{-\sin t}{\cos t^2 + \sin t^2} (-\sin t) dt + \int_{\pi}^{2\pi} \frac{\cos t}{\cos t^2 + \sin t^2} (\cos t) dt = \int_{\pi}^{2\pi} 1 dt = \pi \\ &= - \int_{-C_2} \vec{F} \cdot d\vec{r} \end{aligned}$$

So $-\int_{C_2} \vec{F} \cdot d\vec{r} = \int_{C_1} \vec{F} \cdot d\vec{r} = \pi$. Not path independent.

This is not a contradiction of Theorem 6, since P and Q do not have continuous first order derivatives. They are discontinuous at (0, 0).

17.4 # 3

a) The line integral has three line segments, $\vec{r}_1(t) = \langle t, 0 \rangle$, $\vec{r}_2(t) = \langle 1, 2t \rangle$, $\vec{r}_3(t) = \langle 1-t, 2(1-t) \rangle$. Each will have $0 \leq t \leq 1$.

$$\begin{aligned} \int_C xy dx &= \int_C x(t)y(t)x'(t) dt \\ &= \int_{C_1} x(t)y(t)x'(t) dt + \int_{C_2} x(t)y(t)x'(t) dt + \int_{C_3} x(t)y(t)x'(t) dt \\ &= \int_0^1 t(0)(1) dt + \int_0^1 1(2t)(0) dt + \int_0^1 (1-t)2(1-t)(-1) dt \\ &= 0 + 0 - 2 \int_0^1 (1-t)^2 dt \\ &= -2/3 \end{aligned}$$

$$\begin{aligned} \int_C x^2 y^3 dy &= \int_C x(t)^2 y(t)^3 y'(t) dt \\ &= \int_{C_1} x(t)^2 y(t)^3 y'(t) dt + \int_{C_2} x(t)^2 y(t)^3 y'(t) dt + \int_{C_3} x(t)^2 y(t)^3 y'(t) dt \\ &= \int_0^1 (1)^2 (0)^3 (0) dt + \int_0^1 (1)^2 (2t)^3 (2) dt + \int_0^1 (1-t)^2 2^3 (1-t)^3 (-2) dt \\ &= 0 + 2^4 \int_0^1 t^3 dt - 2^4 \int_0^1 (1-t)^5 dt \\ &= 4 - 8/3 \end{aligned}$$

So $\int_C xy dx + x^2 y^3 dy = -2/3 + 4 - 8/3 = 2/3$.

b)

$$\begin{aligned} \iint_D \left(\frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right) dA &= \iint_D (2xy^3 - x) dA \\ &= \int_0^1 \int_0^{2x} (2xy^3 - x) dy dx \\ &= \int_0^1 \left(\frac{2^5 x^5}{4} - 2x^2 \right) dx \\ &= 2/3 \end{aligned}$$

Of course, they're the same.

17.4 # 9

$$\int_C (y + e^{\sqrt{x}}) dx + (2x + \cos y^2) dy = \iint_D \frac{\partial}{\partial x} (2x + \cos y^2) - \frac{\partial}{\partial y} (y + e^{\sqrt{x}})$$

$$\begin{aligned}
&= \int_0^1 \int_{x^2}^{\sqrt{x}} (2-1) dy dx \\
&= \int_0^1 (\sqrt{x} - x^2) dx \\
&= 1/3
\end{aligned}$$

17.4 # 13

Note that the path as given is negatively oriented. If we use Green's Theorem, we have to remember to switch the sign. $\int_C \vec{F} \cdot d\vec{r} = -\int_{-C} \vec{F} \cdot d\vec{r} = \int \int_D (\frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y}) dA$.

$$\begin{aligned}
\int \int_D (\frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y}) dA &= \int_0^\pi \int_0^{\sin x} (2x - 3y^2) dy dx \\
&= \int_0^\pi (2x \sin x - \sin x^3) dx \\
&= 2 [\sin x - x \cos x]_0^\pi - [-1/3 \sin x^2 \cos x]_0^\pi - 2/3 \int_0^\pi \sin x dx \\
&= 2(0 - 0 + \pi - 0) + 0 + 2/3(-1 - 1) \\
&= 2\pi - 4/3
\end{aligned}$$

So $\int_C \vec{F} \cdot d\vec{r} = 4/3 - 2\pi$.

17.4 # 25

The definition of the moments are $I_y = \int \int_D x^2 \rho(x, y) dA$ and $I_x = \int \int_D y^2 \rho(x, y) dA$. Since ρ is constant, these become $I_y = \rho \int \int_D x^2 dA$ and $I_x = \rho \int \int_D y^2 dA$. If we can find $\vec{F}(x, y) = \langle P, Q \rangle$ such that $\frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} = x^2$ for I_y , then we can use Green's Theorem. Choose $\vec{F} = \langle 0, x^3/3 \rangle$. So

$$I_y = \rho \int \int_D x^2 dA = \rho \int_C \langle 0, x^3/3 \rangle \cdot d\vec{r} = \rho/3 \int_C x^3 \cdot dy$$

Similarly, for I_x , we choose $\vec{F} = \langle -y^3, 0 \rangle$.

$$I_x = \rho \int \int_D y^2 dA = \rho \int_C \langle -y^3/3, 0 \rangle \cdot d\vec{r} = -\rho/3 \int_C y^3 \cdot dx$$

17.5 # 3

$$\begin{aligned}
\vec{\nabla} \cdot \vec{F} &= \langle \frac{\partial}{\partial x}, \frac{\partial}{\partial y}, \frac{\partial}{\partial z} \rangle \cdot \langle 1, x + yz, xy - \sqrt{z} \rangle \\
&= 0 + z - \frac{1}{2\sqrt{z}}
\end{aligned}$$

$$\vec{\nabla} \times \vec{F} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ 1 & x + yz & xy - \sqrt{z} \end{vmatrix} = \hat{i}(x - y) - \hat{j}(y - 0) + \hat{k}(1 - 0)$$

$$\vec{\nabla} \times \vec{F} = \langle x - y, -y, 1 \rangle$$

17.5 # 12

- a) Meaningless, since curl operates on vectors.
- b) Vector field
- c) Scalar field
- d) Vector field
- e) Meaningless, since gradient operates on scalar fields

- f) Vector field
 g) Scalar field
 h) Meaningless, since divergence operates on vector fields
 i) Vector field
 j) Meaningless, since divergence operates on vector fields, but the first divergence would return a scalar field
 k) Meaningless. The cross product works on vectors, but $\text{div}(\mathbf{F})$ is a scalar.
 l) Scalar field. Actually, 0, but that's a scalar.

17.5 # 13

If $\vec{\nabla} \times \vec{F} = \vec{0}$, then \vec{F} is a conservative field. The cross product is $\langle (x-x), (-y+y), (z-z) \rangle = \vec{0}$. A good potential function is $f(x, y, z) = xyz$.

17.6 # 3

For a given value of x , this is clearly a circle in y and z . This is independent of x , so this surface is a cylinder along the x -axis.

17.6 # 17

$$\vec{r}(u, v) = \langle 1, 2, -3 \rangle + u\langle 1, 1, -1 \rangle + v\langle 1, -1, 1 \rangle.$$

17.6 # 21

Spherical coordinates are best: $\rho = 2$, $0 \leq \theta \leq 2\pi$, $0 \leq \phi \leq \pi/4$. This would give

$$\vec{r}(\theta, \phi) = \langle 2 \sin \phi \cos \theta, 2 \sin \phi \sin \theta, 2 \cos \phi \rangle.$$

You could do this in rectangular coordinates, too: Find the limits from

$z = \sqrt{4 - x^2 - y^2} = \sqrt{x^2 + y^2}$ gives $x^2 + y^2 = 2$ for the intersection. But, any circular radius less than this is legal, so we get $z = \sqrt{4 - x^2 - y^2}$, $x^2 + y^2 \leq 2$.

17.6 # 35

S is given by the graph $z = g(x, y) = 4 - x - 2y$ such that $x^2 + y^2 \leq 4$.

$$\begin{aligned} A(S) &= \iint_S dS = \iint_D \sqrt{1 + g_x^2 + g_y^2} dA \\ &= \iint_D \sqrt{1 + 1^2 + 2^2} dA \\ &= \sqrt{6} \iint_D dA \\ &= \sqrt{6} \int_0^{2\pi} \int_0^2 r \, dr \, d\theta \\ &= 4\pi\sqrt{6} \end{aligned}$$

17.6 # 45

$$\vec{r}(u, v) = \langle xu, u + v, u - v \rangle. \quad \vec{r}_u = \langle v, 1, 1 \rangle. \quad \vec{r}_v = \langle u, 1, -2 \rangle.$$

$$\iint_S 1 dS = \iint_D |\vec{r}_u \times \vec{r}_v| \, dA.$$

$$\vec{r}_u \times \vec{r}_v = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ v & 1 & 1 \\ u & 1 & -2 \end{vmatrix} = \hat{i}(-1 - 1) - \hat{j}(-v - u) + \hat{k}(u - v) = \langle -2, u + v, u - v \rangle$$

$$|\vec{r}_u \times \vec{r}_v| = \sqrt{4 + u^2 + v^2 + 2uv + u^2 + v^2 - 2uv} = \sqrt{4 + 2(u^2 + v^2)}.$$

$$\iint_S 1 dS = \iint_D \sqrt{4 + 2(u^2 + v^2)} dA.$$

Since D is a circle in u and v , this integral is easy in polar coordinates. $u = r \cos \theta$. $v = r \sin \theta$.

$$\iint_D \sqrt{4 + 2(u^2 + v^2)} dA = \int_0^{2\pi} \int_0^1 (\sqrt{4 + 2r^2}) r \, dr \, d\theta$$

Make a substitution, $t = 4 + 2r^2$, $dt = 4r \, dr$.

$$\iint_S 1 dS = 2\pi/4 \int_4^6 \sqrt{t} dt = \pi/3(6^{3/2} - 8)$$